Curriculum Vitae
Sebastian Brunner

Personal Data

Birthday	July 1, 1989
Nationality	German
Homepage	sebastian-brunner.github.io

Education

2015 – now **PhD at University Bremen, Chair of Artificial Intelligence**
Topic: Autonomous Optimization of Resource-Aware Robotic Behavior

2011 - 2014 **Computer Science at Technical University Munich, M.Sc.**
Focus: Robotics and Artificial Intelligence

2011 **Exchange Semester at Technical University Lund**, Sweden
Studies in Computer Science

2008 - 2011 **Computer Science at Technical University Munich, B.Sc.**
Subsidiary Subject: Electrical Engineering

Professional Experience

2014 - now **German Aerospace Center - Research Assistant**
Topics: Robotics, AI, task control, autonomous system architectures, belief state modeling, semantic planning and scheduling, continuous integration, software engineering
Robotic Systems: LRU, AIMM, Omnirob, Jaco, LWR
Projects: Arches, EASE SFB, Robex, SpacebotCamp, Euroc, Tapas

2013 - 2014 **German Aerospace Center - Student Research Assistant**
Topics: Spacemouse (3D mouse) integration for robot control, software library for non-linear covariance transformation

2012 - 2014 **Robocup Logistics League - Software Core Developer**
International Competition: 2x first place, 1x second place
Topics: Computer vision, navigation, ROS infrastructure, robot communication

2012 - 2013 **Fortiss Institute - Student Research Assistant**
Topics: UAV control software, sensor fusion, bus systems (I2C, COM, USB), sensor data processing, HiL and SiL simulations

2010 – 2011 **Technical University Munich – Tutor**
Lectures: Algorithms and Data Structures, Operating Systems

Selected Publications

2019	Brunner, S. G.; Dömel, A.; Lehner, P.; Beetz, M. & Stulp, F., **Autonomous Parallelization of Resource-Aware Robotic Task Nodes**, IEEE Robotics and Automation Letters, 4, 2599-2606
2018	Brunner, S. G.; Lehner, P.; Schuster, M. J.; Riedel, S.; Belder, R.; Wedler, A.; Leidner, D.; Beetz, M. & Stulp, F., **Design, Execution, and Post-Mortem Analysis of Prolonged Autonomous Robot Operations**, IEEE Robotics and Automation Letters, 3, 1056-1063
2018	Lehner, P.; Brunner, S. G.; Dömel, A.; Gmeiner, H.; Riedel, S.; Vodermayer, B. & Wedler, A., **Mobile manipulation for planetary exploration**, 2018 IEEE Aerospace Conference, 1-11
2017	Schuster, M. J.; Brunner, S. G.; Bussmann, K.; et al. **Towards Autonomous Planetary Exploration: The Lightweight Rover Unit (LRU), its Success in the SpaceBotCamp Challenge, and Beyond**, Journal of Intelligent & Robotic Systems (JINT), 93, 461-494
2016	Brunner, S. G.; Steinmetz, F.; Belder, R. & Dömel, A., **RAFCON: A Graphical Tool for Engineering Complex, Robotic Tasks**, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
2016	Brunner, S. G.; Steinmetz, F.; Belder, R. & Dömel, A., **RAFCON: a Graphical Tool for Task Programming and Mission Control**, RoboCup 2016: Robot Soccer World Cup XX, Springer Berlin Heidelberg
2016	Schuster, M. J.; Brand, C.; Brunner, S. G.; et al., **The LRU Rover for Autonomous Planetary Exploration and its Success in the SpaceBotCamp Challenge,** ICARSC - IEEE International Conference on Autonomous Robot Systems and Competitions
2014	Brunner, S. G., **Parallel Sparse Bundle Adjustment for Simultaneous Localization and Mapping,** Master Thesis, TU Munich
2013	Jentzsch, S.; Riedel, S.; Denz, S. & Brunner, S. G., Chen, X.; Stone, P.; Sucar, L. & van der Zant, T. (Eds.), **TUMsBendingUnits from TU Munich: RoboCup 2012 Logistics League Champion,** Robot Soccer World Cup XVI, Springer Berlin Heidelberg, 7500, 48-58

Honors and Awards

2012 – 2014	**1st Place, Robocup Logistics League,** Mexico (2012), Netherlands (2013), 2nd Place Brazil (2014)
2012+2013	**Award for Outstanding Student Projects,** Student Council MPI
2011	**DAAD Student Exchange Scholarship,** 2011, for Exchange Semester in Sweden

80636 Munich,
Germany

Phone: +4915902155883
Email: sebastiangeorgbrunner@googlemail.com

Languages

German	Native speaker
English	Fluent
French	Beginner

Skills

Programming	Python, C/C++, Java, SQL, OpenGL, OpenCL
Robotics	ROS, Task Control Languages
Modeling	UML
OS	Linux, Microsoft
Web and Layout	HTML, CSS, Adobe Creative Suite
Frameworks	Github, Gitlab, Jenkins, Redmine, Jira

Interests

Running, Ski-Touring, Traveling